

Theoretical Physics II B – Quantum Mechanics

Lecture 5

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Solutions to previous control questions

4.1 Determine first the transformation matrix \hat{T} through

$$(\hat{T})_{ij} = \langle \psi_i | \phi_j \rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$$

Since all entries are real and because \hat{T} is symmetric, it is self-adjoint: $\hat{T} = \hat{T}^\dagger$. Therefore

$$\begin{aligned} \hat{A} \Big|_{\phi} &= \hat{T}^\dagger \hat{A} \Big|_{\psi} \hat{T} \\ &= \frac{1}{2} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 1 & \epsilon \\ \epsilon & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} = \begin{pmatrix} 1+\epsilon & 0 \\ 0 & 1-\epsilon \end{pmatrix}. \end{aligned}$$

Note: Realising that the $|\phi_{1,2}\rangle$ are the eigenvectors of \hat{A} with eigenvalues $1 \pm \epsilon$ would have yielded the same result.

Solutions to previous control questions (cont'd)

4.2 Eigenvalues follow from characteristic equation,

$$\det \begin{pmatrix} H_{11} - \lambda & H_{12} \\ H_{12} & H_{22} - \lambda \end{pmatrix} = 0$$
$$\longrightarrow \lambda_{1,2} = \frac{H_{11} + H_{22}}{2} \pm \frac{H_{11} - H_{22}}{2} \sqrt{1 + \frac{4H_{12}^2}{(H_{11} - H_{22})^2}}.$$

The eigenvectors are given by solutions of

$$\begin{pmatrix} H_{11} & H_{12} \\ H_{12} & H_{22} \end{pmatrix} \begin{pmatrix} \lambda_{i1} \\ \lambda_{i2} \end{pmatrix} = \lambda_i \begin{pmatrix} \lambda_{i1} \\ \lambda_{i2} \end{pmatrix}$$
$$\longrightarrow \lambda_{i2} = \frac{\lambda_i - H_{11}}{H_{12}} \lambda_{i1} \longrightarrow \vec{\lambda}_i = \begin{pmatrix} H_{12} \\ \lambda_i - H_{11} \end{pmatrix}.$$

Postulates for measurements in Quantum Mechanics

Postulate 3: All viable quantum mechanical observables can be represented as Hermitean operators.

Postulate 4: The only result of *one precise measurement* of an observable \mathcal{A} is *one of the eigenvalues* of the associated Hermitean operator \hat{A} . The measurement will force the state vector of the system to become one of the corresponding eigenvectors.

Postulate 5: The result of a *series of measurements* of this observable over an ensemble of systems in the same state $|\Phi\rangle$, the *expectation value*, is given by

$$\langle \mathcal{A} \rangle_{|\Phi\rangle} = \frac{\langle \Phi | \hat{A} | \Phi \rangle}{\langle \Phi | \Phi \rangle}.$$

Expansion in eigenkets/eigenfunctions

- In postulate 3, *all observables* in Quantum Mechanics were connected with Hermitean operators, which have an orthonormal set of eigenvectors, spanning the full vector space as a base.
- This implies

Postulate 6: Every ket representing a state of a dynamical system can be expressed as a *linear combination* of the normalised eigenkets of a Hermitean operator \hat{O} associated to an observable O .

Expansion in eigenkets/eigenfunctions and measurements

- Using postulate 6 and writing

$$|\psi\rangle = \sum_i c_i |\lambda_i\rangle \quad \text{with} \quad c_i = \langle \lambda_i | \psi \rangle \quad \text{and} \quad \sum_i |c_i|^2 = 1$$

therefore yields (with postulate 4)

$$\begin{aligned} \langle \mathcal{O} \rangle_\psi &\equiv \langle \psi | \hat{\mathcal{O}} | \psi \rangle = \sum_{i,k} c_i^* c_k \langle \lambda_i | \hat{\mathcal{O}} | \lambda_k \rangle \\ &= \sum_{i,k} c_i^* c_k \lambda_k \langle \lambda_i | \lambda_k \rangle = \sum_{i,k} c_i^* c_k \lambda_k \delta_{ik} = \sum_i |c_i|^2 \lambda_i, \end{aligned}$$

which can be interpreted as an *weighted* average – the expectation value – of the eigenvalues of $\hat{\mathcal{O}}$, with weights given by the probabilities $\mathcal{P}_i^{|\psi\rangle} = |c_i|^2$ of the system to be in the i th eigenstate, described by $|\psi\rangle$.

Expansion in eigenkets/eigenfunctions and measurements

- The terms $c_i = \langle \lambda_i | \psi \rangle$ are the *probability amplitudes* for the system to be found in $|\lambda_i\rangle$.
- As a by-product of postulate 4, a *single* measurement of \mathcal{O} will lead to a collapse of the linear combination of $|\psi\rangle$ to a single eigenket $|\lambda_i\rangle$, which is chosen according to the probabilities $|c_i|^2$:

$$|\psi\rangle = \sum_i \langle \lambda_i | \psi \rangle |\lambda_i\rangle \xrightarrow{\mathcal{O}} |\lambda_i\rangle$$

- A subsequent immediate measurement of the same observable, \mathcal{O} , of the system then yields λ_i with certainty. This can be used to *prepare* a set of systems.

Partially continuous spectrum

- Now, assume a spectrum of \hat{O} , that consists of some discrete eigenvalues plus a range of continuous ones. Then:

$$|\psi\rangle = \sum_i c_i |\lambda_i\rangle + \int dI c(I) |\lambda(I)\rangle ,$$

with $c_i = \langle \lambda_i | \psi \rangle$ and, in a straightforward extension, $c(I) = \langle \lambda(I) | \psi \rangle$.

- Using the orthonormality of the eigenvectors

$$\langle \lambda_i | \lambda_j \rangle = \delta_{ij} , \quad \langle \lambda_i | \lambda(I) \rangle = 0 , \quad \text{and} \quad \langle \lambda(k) | \lambda(I) \rangle = \delta(k - I)$$

therefore yields the expectation value for the observable \mathcal{O}

$$\langle \mathcal{O} \rangle_\psi = \sum_i |c_i|^2 \lambda_i + \int dI |c(I)|^2 \lambda(I) .$$

Partially continuous spectrum - density of states

- As before, for the discrete part of the spectrum, $c_i = \langle \lambda_i | \psi \rangle$ denotes the *probability amplitude* for finding the system in state $|\lambda_i\rangle$, and therefore $|c_i|^2$ is the corresponding probability.
- For the continuous part, the states $\lambda(l)$ are lying dense, and one may introduce a *density of states*

$$\rho(l) = \frac{di}{dl},$$

the number of states in a unit interval of l .

- This density can be used to normalise the eigenkets $|\lambda(l)\rangle$.

Operator functions

- Defining monomials of an operator \hat{L} as $\hat{L}^n = \underbrace{\hat{L}\hat{L}\dots\hat{L}}_{n \text{ factors}}$

allows to define operator functions $\mathcal{F}(\hat{L})$ through their Taylor-expansion

$$\mathcal{F}(\hat{L}) = f_0 \hat{\mathbf{1}} + f_1 \hat{L}^1 + f_2 \hat{L}^2 + \dots$$

and in particular

$$e^{\hat{L}} = \exp(\hat{L}) = \sum_{n=0}^{\infty} \frac{1}{n!} \hat{L}^n.$$

- Differentiation of such functions with respect to operators is a bit cumbersome to define, but straightforward to exercise:

$$\frac{\partial}{\partial \hat{L}}(\mathcal{F} + \mathcal{G}) = \frac{\partial \mathcal{F}}{\partial \hat{L}} + \frac{\partial \mathcal{G}}{\partial \hat{L}}, \quad \frac{\partial}{\partial \hat{L}}(\mathcal{F}\mathcal{G}) = \frac{\partial \mathcal{F}}{\partial \hat{L}} \mathcal{G} + \mathcal{G} \frac{\partial \mathcal{G}}{\partial \hat{L}},$$

$$\frac{\partial \hat{L}^n}{\partial \hat{L}} = n \hat{L}^{n-1}, \quad \frac{\partial e^{\hat{L}}}{\partial \hat{L}} = e^{\hat{L}}.$$

Commutators

The difference $\hat{L}\hat{M} - \hat{M}\hat{L} \equiv [\hat{L}, \hat{M}] \equiv [\hat{L}, \hat{M}]_-$ is called the commutator of the two operators and it has the following properties:

- $[\hat{L}, \hat{M}] = -[\hat{M}, \hat{L}]$ and, as a consequence, $[\hat{L}, \hat{L}] = 0$;
- $[\hat{L}, c\hat{\mathbf{1}}] = 0 \quad \forall c \in \mathbf{C}$;
- $[\hat{L}, c\hat{M}] = c[\hat{L}, \hat{M}]$;
- $[\hat{L}_1 + \hat{L}_2, \hat{M}] = [\hat{L}_1, \hat{M}] + [\hat{L}_2, \hat{M}]$;
- $[\hat{L}_1\hat{L}_2, \hat{M}] = [\hat{L}_1, \hat{M}]\hat{L}_2 + \hat{L}_1[\hat{L}_2, \hat{M}]$;
- $[\hat{M}, \hat{L}_1\hat{L}_2] = [\hat{M}, \hat{L}_1]\hat{L}_2 + \hat{L}_1[\hat{M}, \hat{L}_2]$;
- $[\hat{L}_1, [\hat{L}_2, \hat{L}_3]] + [\hat{L}_2, [\hat{L}_3, \hat{L}_1]] + [\hat{L}_3, [\hat{L}_1, \hat{L}_2]] = 0$.

Learning outcomes

- Results of measurements in Quantum Mechanics: Eigenvalue vs. expectation value.
- Operator functions
- Commutators and their basic properties

Control questions

- 5.1 The Hamilton operator \hat{H} of a system and an operator \hat{O} related to a measured quantity are given by

$$\hat{H} = \hbar\omega \begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix} \quad \text{and} \quad \hat{O} = \mu \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}.$$

The system is described by a *normalised* state vector

$$|\psi\rangle = \sum_{i=1}^2 c_i |v_i\rangle, \quad \text{where} \quad |v_1\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad \text{and} \quad |v_2\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}.$$

- (a) What is the relation of the (potentially complex) quantities c_1 and c_2 to maintain $\langle\psi|\psi\rangle = 1$?
- (b) What are possible energies that can be found when measuring the energy related to the state $|\psi\rangle$?
- (c) What are the expectation values of \hat{H} and \hat{O} , if the system is in a state $|\psi\rangle$?

Control questions

5.2 The Pauli matrices $\hat{\sigma}_{x,y,z}$ are given by

$$\hat{\sigma}_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \hat{\sigma}_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad \hat{\sigma}_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}.$$

Prove by direct calculation that

$$[\hat{\sigma}_i, \hat{\sigma}_j] = 2i\epsilon_{ijk}\hat{\sigma}_k \quad \text{for} \quad \{i, j, k\} = \{1, 2, 3\} = \{x, y, z\},$$

where ϵ_{ijk} is the Levi-Civita tensor (totally anti-symmetric tensor of rank 3) with $\epsilon_{123} = 1$.