

Theoretical Physics II B – Quantum Mechanics

Lecture 14

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Solutions to previous control questions

13.1 (a) Commutators:

$$\begin{aligned} [\hat{J}^2, \hat{J}_k] &= \sum_{i=1}^3 (\hat{J}_i^2 \hat{J}_k - \hat{J}_k \hat{J}_i^2) = \sum_{i=1, i \neq k}^3 (\hat{J}_i^2 \hat{J}_k - \hat{J}_k \hat{J}_i^2) \\ &= \sum_{i=1, i \neq k}^3 \left\{ \hat{J}_i [\hat{J}_i, \hat{J}_k] + \hat{J}_i \hat{J}_k \hat{J}_i - \hat{J}_k \hat{J}_i \hat{J}_i \right\} \\ &= \sum_{i=1, i \neq k}^3 \left\{ \hat{J}_i [\hat{J}_i, \hat{J}_k] + [\hat{J}_i, \hat{J}_k] \hat{J}_i \right\} \\ &= \sum_{i,j=1, i,j \neq k, i \neq j}^3 i \hbar \epsilon_{ikj} \left\{ \hat{J}_i \hat{J}_j + \hat{J}_j \hat{J}_i \right\} = 0 \end{aligned}$$

because the Levi-Civita symbol is anti-symmetric under the direct exchange of i and j :

$$\epsilon_{ikj} = -\epsilon_{jki}.$$

$$[\hat{J}_+, \hat{J}_-] = [\hat{J}_x + i\hat{J}_y, \hat{J}_x - i\hat{J}_y] = -i[\hat{J}_x, \hat{J}_y] + i[\hat{J}_y, \hat{J}_x] = 2\hbar\hat{J}_z.$$

$$[\hat{J}_\pm, \hat{J}_z] = [\hat{J}_x \pm i\hat{J}_y, \hat{J}_z] = -i\hbar\hat{J}_y \mp \hbar\hat{J}_x = \mp\hbar(\hat{J}_x \pm i\hat{J}_y) = \mp\hbar\hat{J}_\pm$$

$$[\hat{J}_\pm, \hat{J}^2] = [\hat{J}_x, \hat{J}^2] \pm i[\hat{J}_y, \hat{J}^2] = 0.$$

(b) The solution follows from rearranging the result of

$$\hat{J}_+\hat{J}_- = \hat{J}_x^2 + \hat{J}_y^2 + i(\hat{J}_y\hat{J}_x - \hat{J}_x\hat{J}_y) = \hat{J}^2 - \hat{J}_z^2 + \hbar\hat{J}_z.$$

Using that $\hat{J}_- |j, m\rangle = c_{-,jm} |j, m-1\rangle$ we find

$$\begin{aligned} |c_{-,jm}|^2 \langle j, m-1 | j, m-1 \rangle &= \langle j, m-1 | (\hat{J}_-^\dagger \hat{J}_-) | j, m \rangle \\ &= \langle j, m-1 | (\hat{J}_+ \hat{J}_-) | j, m \rangle = \langle j, m-1 | (\hat{J}^2 - \hat{J}_z^2 + \hbar \hat{J}_z) | j, m \rangle \\ &= \hbar^2 [j(j+1) - m(m-1)] \langle j, m-1 | j, m-1 \rangle \end{aligned}$$

and therefore

$$|c_{-,jm}|^2 = \hbar^2 [j(j+1) - m(m-1)] = \hbar^2 (j-m+1)(j+m).$$

13.2 Express $\hat{L}_{x,y}$ through \hat{L}_{\pm} :

$$\hat{L}_x = \frac{1}{2} (\hat{L}_+ + \hat{L}_-) \quad \text{and} \quad \hat{L}_y = \frac{1}{2i} (\hat{L}_+ - \hat{L}_-) .$$

Use the matrix elements of the ladder operators

$$\langle l' m' | \hat{L}_{\pm} | l m \rangle = \hbar \sqrt{(l \mp m)(l \pm m + 1)} \delta_{l' l} \delta_{m' m \pm 1}$$

to realise that their expectation value vanishes, since in this case we want to have $\langle l m | \hat{L}_{\pm} | l m \rangle$ and thus $m' = m \neq m \pm 1$.

On the other hand,

$$\hat{L}_x^2 = \frac{1}{4} \left(\hat{L}_+^2 + \hat{L}_-^2 + \hat{L}_+ \hat{L}_- + \hat{L}_- \hat{L}_+ \right) = \frac{1}{4} \left(\hat{L}_+^2 + \hat{L}_-^2 + 2\hat{L}_-^2 - 2\hat{L}_z^2 \right)$$

and similarly

$$\hat{L}_y^2 = -\frac{1}{4} \left(\hat{L}_+^2 + \hat{L}_-^2 - \hat{L}_+ \hat{L}_- - \hat{L}_- \hat{L}_+ \right) = -\frac{1}{4} \left(\hat{L}_+^2 + \hat{L}_-^2 - 2\hat{L}_-^2 + 2\hat{L}_z^2 \right)$$

yields

$$\langle lm | \hat{L}_{x,y}^2 | lm \rangle = \frac{1}{2} \langle lm | \left(\hat{L}_-^2 - \hat{L}_z^2 \right) | lm \rangle = \hbar^2 \frac{l(l+1) - m^2}{2}.$$

Reminder: Commutation relations etc.

- Remember the commutation relations

$$[\hat{J}_i, \hat{J}_j] = i\hbar\epsilon_{ijk}\hat{J}_k, \quad [\hat{J}^2, \hat{J}_k] = 0$$

and the ladder operators $\hat{J}_{\pm} = \hat{J}_x \pm i\hat{J}_y$ with

$$[\hat{J}_+, \hat{J}_-] = 2\hbar\hat{J}_z, \quad [\hat{J}_z, \hat{J}_{\pm}] = \pm\hbar\hat{J}_{\pm} \quad \text{and} \quad [\hat{J}^2, \hat{J}_{\pm}] = 0.$$

- Eigenvalues and eigenkets read

$$\hat{J}^2 |jm\rangle = j(j+1)\hbar^2 |jm\rangle \quad \text{and} \quad \hat{J}_z |jm\rangle = m\hbar |jm\rangle.$$

- j and m are non-negative integers or half-integers, and

$$m \in \{-j, -j+1, -j+2, \dots, j-1, j\}.$$

Matrix elements of angular momentum operators

- The eigenkets $|jm\rangle$ form an orthonormal base: $\langle j' m' | jm \rangle = \delta_{jj'} \delta_{mm'}$
- Operator sandwiches:

$$\langle j' m' | \hat{j}^2 | jm \rangle = j(j+1)\hbar^2 \delta_{jj'} \delta_{mm'} \quad \text{and} \quad \langle j' m' | \hat{j}_z | jm \rangle = m\hbar \delta_{jj'} \delta_{mm'}$$

- Action of ladder operators:

$$\hat{J}_{\pm} |jm\rangle = \sqrt{(j \mp m)(j \pm m + 1)} \hbar |j(m \pm 1)\rangle$$

Angular momentum operators for spin- $\frac{1}{2}$

- Eigenvalue j also called the **spin**.
- Angular momentum operators for $j = \frac{1}{2}$ proportional to Pauli's:

$$\hat{J}_i \xrightarrow{j=\frac{1}{2}} \frac{\hbar}{2} \hat{\sigma}_i ,$$

with

$$\hat{\sigma}_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} , \quad \hat{\sigma}_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} , \quad \hat{\sigma}_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} .$$

- Easy to check: \hat{S}_i have same algebra as \hat{J}_i .
- Additional identities for $\hat{\sigma}_i$:

$$\begin{aligned} [\hat{\sigma}_i, \hat{\sigma}_j] &= 2i\epsilon_{ijk}\hat{\sigma}_k , \quad \{\hat{\sigma}_i, \hat{\sigma}_j\} = 2\delta_{ij}\hat{\mathbf{1}} , \quad \hat{\sigma}_i^\dagger = \hat{\sigma}_i , \\ \sigma_i^2 &= \hat{\mathbf{1}} , \quad \det(\hat{\sigma}_i) = -1 , \quad \text{Tr}(\hat{\sigma}_i) = 0 . \end{aligned}$$

Finite rotations for spin- $\frac{1}{2}$

- Consider now a two-component ket $|\alpha\rangle$ to be rotated by rotation \mathcal{R} (around z-axis by ϕ), of course generated by \hat{S}_z :

$$|\alpha\rangle \xrightarrow{\mathcal{R}} |\alpha'\rangle = \hat{R}_z^{(\frac{1}{2})}(\phi) |\alpha\rangle = \exp\left(-\frac{i\hat{S}_z\phi}{\hbar}\right) |\alpha\rangle$$

- Check for rotation: Calculate $\langle\hat{S}_x\rangle_{|\alpha\rangle}$ before and after rotation.

$$\begin{aligned}\langle\alpha'|\hat{S}_x|\alpha'\rangle &= \left\langle\alpha\left|\exp\left(\frac{i\hat{S}_z\phi}{\hbar}\right)\hat{S}_x\exp\left(-\frac{i\hat{S}_z\phi}{\hbar}\right)\right|\alpha\right\rangle \\ &= \langle\alpha|\hat{S}_x|\alpha\rangle \cos\phi - \langle\alpha|\hat{S}_y|\alpha\rangle \sin\phi.\end{aligned}$$

(To see this use the identity for $\exp(\hat{L})\hat{M}\exp(-\hat{L})$ from lecture 4.)

Rotating the kets in spin- $\frac{1}{2}$ representation

- When applied on expectation values, the rotations generated by the angular momentum matrices deliver the correct behaviour.
- Now let's see what happens when acting on a ket alone.
Decompose $|\alpha\rangle$ into the two eigenkets of \hat{S}_z , $|\uparrow\rangle$ and $|\downarrow\rangle$:

$$|\alpha\rangle = \alpha_{\uparrow} |\uparrow\rangle + \alpha_{\downarrow} |\downarrow\rangle .$$

- Be ready for a surprise! Rotate by 2π :

$$\begin{aligned} |\alpha'\rangle &= \exp\left(-\frac{2i\pi\hat{S}_z}{\hbar}\right) |\alpha\rangle = \exp(-i\pi\hat{\sigma}_z) |\alpha\rangle \\ &= \exp(-i\pi)\alpha_{\uparrow} |\uparrow\rangle + \exp(i\pi)\alpha_{\downarrow} |\downarrow\rangle = -\alpha_{\uparrow} |\uparrow\rangle - \alpha_{\downarrow} |\downarrow\rangle = -|\alpha\rangle . \end{aligned}$$

- A rotation by 2π is just half the way around - for a full rotation of a ket one needs to rotate by 4π .

General rotations for spin- $\frac{1}{2}$

- In general, rotations can be characterised by a rotation axis \underline{n} ($\underline{n}^2 = 1$) and an angle ϕ .

Therefore the rotation operator in the spin- $\frac{1}{2}$ representation reads

$$\hat{R}^{(\frac{1}{2})}(\underline{n}, \phi) \equiv \hat{R}^{(\frac{1}{2})}(\underline{\phi}) = \exp\left(-\frac{i\hat{\underline{\sigma}} \cdot \underline{n}\phi}{2}\right)$$

- In general,

$$\hat{\underline{\sigma}} \cdot \underline{a} = \begin{pmatrix} a_3 & a_1 - ia_2 \\ a_1 + ia_2 & -a_3 \end{pmatrix} \quad \text{and} \quad (\hat{\underline{\sigma}} \cdot \underline{a})^2 = |\underline{a}|^2$$

- Therefore

$$\exp\left(-\frac{i\hat{\underline{\sigma}} \cdot \underline{n}\phi}{2}\right) = \hat{\mathbf{1}} \cos\left(\frac{\phi}{2}\right) - i\hat{\underline{\sigma}} \cdot \underline{n} \sin\left(\frac{\phi}{2}\right).$$

Euler rotations

- From classical mechanics: General rotations of a rigid body can be accomplished in three steps, a.k.a. **Euler rotations**. They are characterised by three angles α , β , and γ around three axes (z, y, and z-axis):

$$\begin{aligned}\mathcal{R}(\underline{n}, \phi) &= \mathcal{R}(\alpha, \beta, \gamma) = \mathcal{R}_z(\alpha)\mathcal{R}_y(\beta)\mathcal{R}_z(\gamma) \\ \longrightarrow \hat{R}(\mathcal{R}) &= \hat{R}(\alpha, \beta, \gamma) = \hat{R}_z(\alpha)\hat{R}_y(\beta)\hat{R}_z(\gamma)\end{aligned}$$

- Because $[\hat{J}_-, \hat{J}_i] = 0$

$$\hat{J}_-^2 \hat{R}(\mathcal{R}) |jm\rangle = \hat{R} \hat{J}_-^2(\mathcal{R}) |jm\rangle = j(j+1)\hbar^2 \hat{R}(\mathcal{R}) |jm\rangle .$$

This means that **under rotations the j values are constant**.

- Thus: Only need j -representations of the \hat{J}_i .

Matrix elements of rotation operators

- This implies that it makes sense to characterise the rotation operators through matrix elements $\hat{R}_{m'm}^{(j)}(\mathcal{R})$:

$$\hat{R}_{m'm}^{(j)}(\mathcal{R}) = \left\langle jm' \left| \exp \left(-\frac{i \hat{\mathbf{J}} \cdot \mathbf{n} \phi}{\hbar} \right) \right| jm \right\rangle$$

In other words the rotation matrix is given by the individual amplitudes for a rotated state to be in state $|jm'\rangle$ when the original state was $|jm\rangle$:

$$\hat{R}(\mathcal{R}) |jm\rangle = \sum_{m'} |jm'\rangle \langle jm' | \hat{R} | jm \rangle .$$

Properties

- Composition and inverse:

$$\sum_{m'} \hat{R}_{m'm}^{(j)}(\mathcal{R}_1) \hat{R}_{m'm''}^{(j)}(\mathcal{R}_2) = \hat{R}_{mm''}^{(j)}(\mathcal{R}_1 \times \mathcal{R}_2)$$

$$\hat{R}_{m'm}^{(j)}(\mathcal{R}^{-1}) = \hat{R}_{mm'}^{(j)*}(\mathcal{R}).$$

The \hat{R} operators are unitary, since the \hat{J}_i are Hermitian.

- Realize that the $|jm\rangle$ are eigenstates of \hat{J}_z :

$$\begin{aligned} & \hat{R}_{m'm}^{(j)}(\alpha, \beta, \gamma) \\ &= \left\langle jm' \left| \exp\left(-\frac{i\hat{J}_z\alpha}{\hbar}\right) \exp\left(-\frac{i\hat{J}_y\beta}{\hbar}\right) \exp\left(-\frac{i\hat{J}_z\gamma}{\hbar}\right) \right| jm \right\rangle \\ &= \exp[-i(m'\alpha + m\gamma)] \left\langle jm' \left| \exp\left(-\frac{i\hat{J}_y\beta}{\hbar}\right) \right| jm \right\rangle \end{aligned}$$

Euler rotations for spin- $\frac{1}{2}$ systems

- For spin- $\frac{1}{2}$ systems therefore

$$\begin{aligned}\hat{R}^{(\frac{1}{2})}(\alpha, \beta, \gamma) &= \exp\left(-\frac{i\hat{\sigma}_3\alpha}{2}\right) \exp\left(-\frac{i\hat{\sigma}_2\beta}{2}\right) \exp\left(-\frac{i\hat{\sigma}_3\gamma}{2}\right) \\ &= \begin{pmatrix} \exp\left[-\frac{i(\alpha+\gamma)}{2}\right] \cos \frac{\beta}{2} & -\exp\left[-\frac{i(\alpha-\gamma)}{2}\right] \sin \frac{\beta}{2} \\ \exp\left[\frac{i(\alpha-\gamma)}{2}\right] \sin \frac{\beta}{2} & \exp\left[\frac{i(\alpha+\gamma)}{2}\right] \cos \frac{\beta}{2} \end{pmatrix}\end{aligned}$$

- This is a unimodular unitary operator (more in homework question).
- The reduced matrix elements read:

$$\left\langle \frac{1}{2}m' \left| \exp\left(-\frac{i\hat{J}_y\beta}{\hbar}\right) \right| \frac{1}{2}m \right\rangle = \begin{pmatrix} \cos \frac{\beta}{2} & -\sin \frac{\beta}{2} \\ \sin \frac{\beta}{2} & \cos \frac{\beta}{2} \end{pmatrix}$$

Euler rotations for spin-1 systems

- Missing ingredient: spin-1 representation of \hat{J}_y .
- From the identity $\hat{J}_y = \frac{\hat{J}_+ - \hat{J}_-}{2i}$ and the form of the ladder operators:

$$\left(\hat{J}_y^{(j=1)}\right)_{m'm} = \frac{i\hbar}{\sqrt{2}} [\delta_{m'(m-1)} - \delta_{m'(m+1)}] = \frac{i\hbar}{\sqrt{2}} \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix}$$

Therefore,

$$\left\langle 1m' \left| \exp\left(-\frac{i\hat{J}_y\beta}{\hbar}\right) \right| 1m \right\rangle = \begin{pmatrix} \frac{1}{2}(1 + \cos\beta) & -\frac{1}{\sqrt{2}}\sin\beta & \frac{1}{2}(1 - \cos\beta) \\ \frac{1}{\sqrt{2}}\sin\beta & \cos\beta & -\frac{1}{\sqrt{2}}\sin\beta \\ \frac{1}{2}(1 - \cos\beta) & \frac{1}{\sqrt{2}}\sin\beta & \frac{1}{2}(1 + \cos\beta) \end{pmatrix}$$

Learning outcomes

- Finite rotations and Euler angles
- Matrix representation of finite rotations through angular momentum operators: unitary matrices.
- Rotations do not change spin j .
- Effective form for evaluating them:

$$\hat{R}_{m'm}^{(j)}(\alpha, \beta, \gamma) = \exp[-i(m'\alpha + m\gamma)] \left\langle jm' \left| \exp\left(-\frac{i\hat{J}_y\beta}{\hbar}\right) \right| jm \right\rangle$$

- How to construct representations for spin $\frac{1}{2}$ and spin 1.

Control questions

14.1 Some algebra.

(a) Check that the following relations hold true:

$$\begin{aligned}(\hat{\underline{\sigma}} \cdot \underline{a})(\hat{\underline{\sigma}} \cdot \underline{b}) &= \underline{a} \cdot \underline{b} \hat{\mathbf{1}} + i \hat{\underline{\sigma}} \cdot (\underline{a} \times \underline{b}) \\(\hat{\underline{\sigma}} \cdot \underline{a})^2 &= |\underline{a}|^2 \hat{\mathbf{1}} \\ \exp\left(-\frac{i \hat{\underline{\sigma}} \cdot \underline{n} \phi}{2}\right) &= \hat{\mathbf{1}} \cos\left(\frac{\phi}{2}\right) - i \hat{\underline{\sigma}} \cdot \underline{n} \sin\left(\frac{\phi}{2}\right) \quad \text{for } |\underline{n}|^2 = 1.\end{aligned}$$

(b) A 2×2 matrix is called unimodular, if it can be written as

$$\begin{pmatrix} a & b \\ -b^* & a^* \end{pmatrix} \quad \text{with } |a|^2 + |b|^2 = 1.$$

Show that

$$\hat{U} = [a_0 + i \hat{\underline{\sigma}} \cdot \underline{a}] [a_0 - i \hat{\underline{\sigma}} \cdot \underline{a}]^{-1}$$

with real numbers a_0 and $\underline{a} = (a_1, a_2, a_3)$ forms an unitary unimodular matrix.

14.2 $j = 1$ representations.

- (a) Explicitly write the 3×3 matrix for $\langle (j = 1)m' | \hat{J}_y | (j = 1)m \rangle$.
- (b) By explicitly calculating powers of $\hat{J}_y^{(j=1)}$, show that

$$\exp\left(-\frac{i\hat{J}_y^{(j=1)}\beta}{\hbar}\right) = \hat{\mathbf{1}} - i\frac{\hat{J}_y^{(j=1)}}{\hbar} \sin \beta - \left(\frac{\hat{J}_y^{(j=1)}}{\hbar}\right)^2 (1 - \cos \beta).$$

- (c) Use the findings of (a) and (b) to prove that

$$\left\langle 1m' \left| \exp\left(-\frac{i\hat{J}_y\beta}{\hbar}\right) \right| 1m \right\rangle = \begin{pmatrix} \frac{1}{2}(1 + \cos \beta) & -\frac{1}{\sqrt{2}} \sin \beta & \frac{1}{2}(1 - \cos \beta) \\ \frac{1}{\sqrt{2}} \sin \beta & \cos \beta & -\frac{1}{\sqrt{2}} \sin \beta \\ \frac{1}{2}(1 - \cos \beta) & \frac{1}{\sqrt{2}} \sin \beta & \frac{1}{2}(1 + \cos \beta) \end{pmatrix}$$