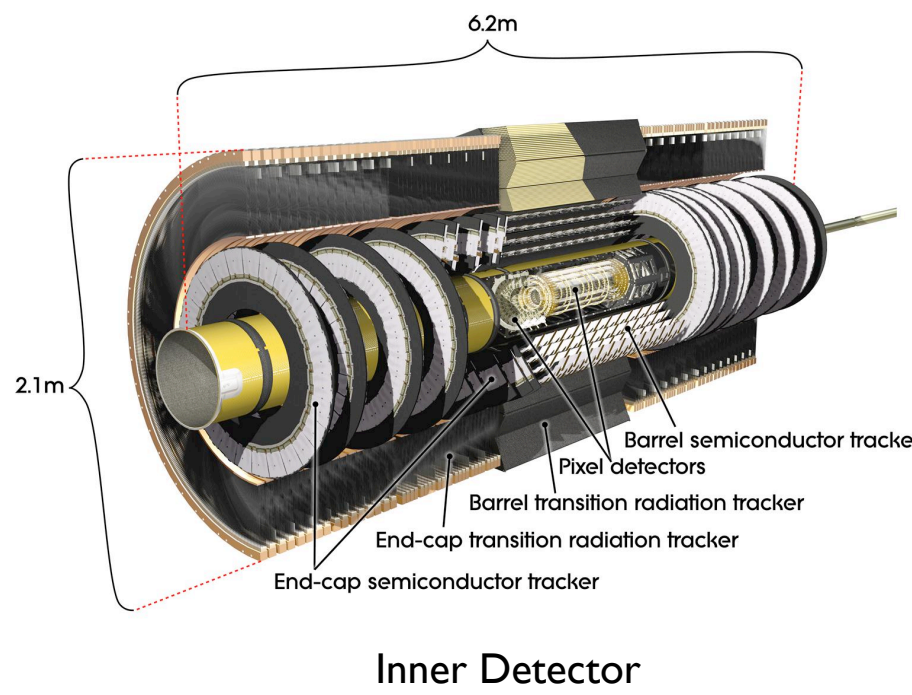


## The ATLAS Inner Detector

The **ID** (Inner Detector) is the inner most system tracker of **ATLAS** (A Toroidal LHC Apparatus). It is designed to provide hermetic and robust pattern recognition, excellent momentum resolution and both primary and secondary vertex reconstruction for charged tracks. The **ID** is composed by three sub-detectors: **Pixel**, **SCT** (SemiConductor Tracker) and **TRT** (Transition Radiation Tracker).

|                      | Pixel Detector<br>Pixel                                  | SCT Detector<br>SemiConductor Tracker           | TRT Detector<br>Transition Radiation Tracker  |
|----------------------|--|---|---|
| <b>Measurement</b>   | Discrete space-point                                     | Stereo pairs of silicon micro-strip             | Average of 30 hits per track  |
| <b>Detector type</b> | Pixel detector   | Micro-strip silicon detectors                   | Gaseous straw tube elements   |
| <b>Detector Size</b> | Pixel size: 50x400 μm <sup>2</sup><br>All modules equals | Micro-strip pitch: ~ 80 μm<br>6 different types | Diameter: 4 mm<br>Length: 144 cm barrel, 37 cm EC   |
| <b>Resolution</b>    | 14x115 μm <sup>2</sup> (*)                               | 23μm (Rφ) , 580 μm (z)(*)                       | 130 μm (*)  |
| <b>Modules</b>       | 1744   | 4088  | 176   |
| <b>Layout</b>        | 3 layers (barrel)<br>2x3 discs (end-cap)                 | 4 layers (barrel)<br>2x9 discs (end-cap)        | 73 layers in 3 rings (barrel)<br>2x160 straw planes in 40 four-plane assembly units (end-cap) |

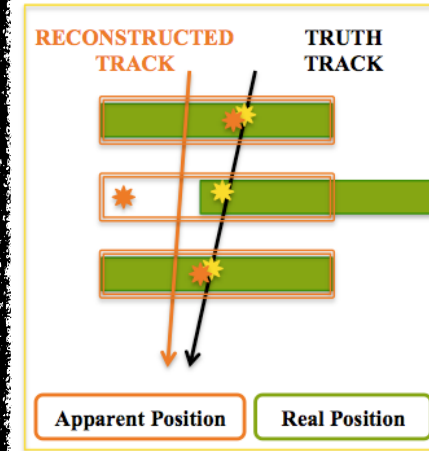


Inner Detector

(\*) The ATLAS Experiment at the CERN Large hadron Collider, JINST3 S08003

## Alignment Problem and Requirements

The detector misalignments affect the track parameters resolution.



The strategy to solve the alignment problem has different steps:

- **Assembly and survey measurements:** External measurements of the as-built detector.
- **Frequency Scanning Interferometry:** A laser alignment monitoring system of the SCT.
- **Track based alignment algorithms:** To achieve the ultimate precision (μm).

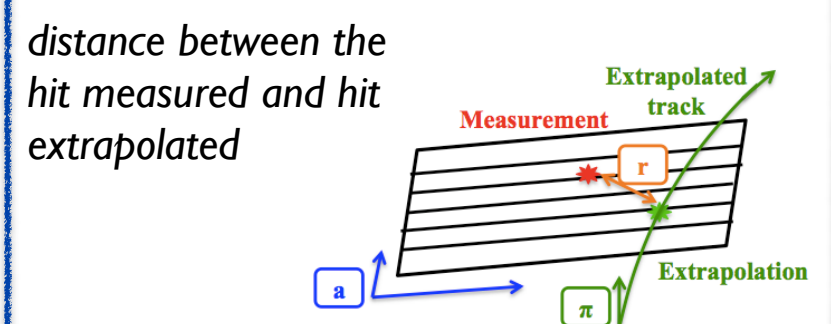
**REQUIREMENTS:** The knowledge of the alignment constants should not lead to a significant degradation of the track parameters beyond the intrinsic tracker resolution to achieve the ATLAS physics goals (degradation of tracking resolution less than 20%).

| Direction | Pixel's |         | SCT    |         |
|-----------|---------|---------|--------|---------|
|           | Barrel  | End-Cap | Barrel | End-Cap |
| Rφ (μm)   | 7       | 7       | 12     | 12      |
| Z (μm)    | 20      | 100     | 50     | 200     |

## Track Based alignment algorithms

The alignment algorithms work with a track  $\chi^2$  sensitive to misalignments. The  $\chi^2$  is built from the track residuals. The  $\chi^2$  is an implicit function of the alignment parameters and it has a minimum in the aligned geometry.

**residuals:**  $r = hit_{measured} - hit(\pi, a)_{extrapolated}$



**$\chi^2$  definition:**

$$\chi^2 = \sum_{Tracks} r^T(\pi, a) V^{-1} r(\pi, a)$$

Where  $r$  are the residuals that depend on track parameters ( $\pi$ ) and alignment parameters ( $a$ ).

**$\chi^2$  minimization:**

The algorithms use the  $\chi^2$  minimization with respect alignment parameters to find the real geometry.

The ID has 6008 modules to align. Most of the modules have 6 DoFs. There are several alignment algorithms working in the ID detector:

### SILICON SYSTEM

#### GlobalChi2:

- Based on the  $\chi^2$  minimization.
- Uses biased residuals.
- Inter module correlation and Multiple Coulomb Scattering is taken into account.
- Huge symmetric matrices are created (34992 DoFs)

#### LocalChi2:

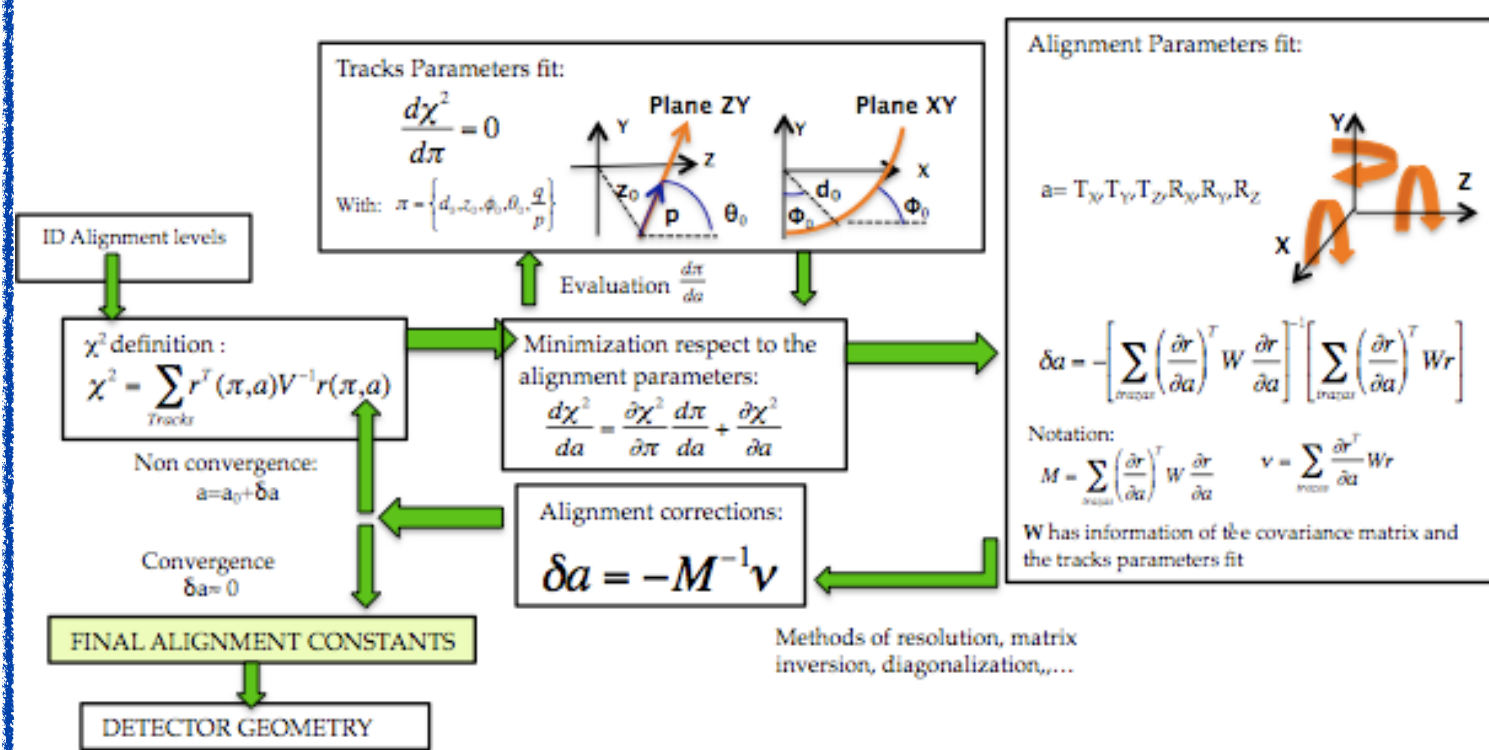
- Same principle as the GlobalChi2 algorithm.
- Unbiased residuals.
- No dependence with respect to the track parameters.
- No Multiple Coulomb Scattering.
- Needs to solve 6x6 matrices (6 DoFs per module).

#### Robust:

- Uses centre residuals and overlap distributions.
- Uses local x and y residuals.
- Overlap residuals for adjacent modules.
- 3 DoFs per module (plane parameters: Tx, Ty, Rz)

### TRT SYSTEM

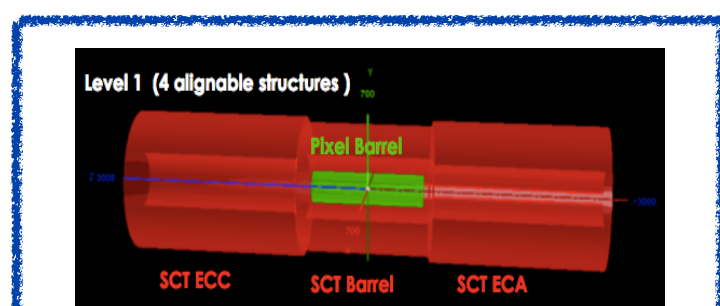
- Based on the  $\chi^2$  minimization.
- Inter module correlation.
- TRT with respect to silicon system.



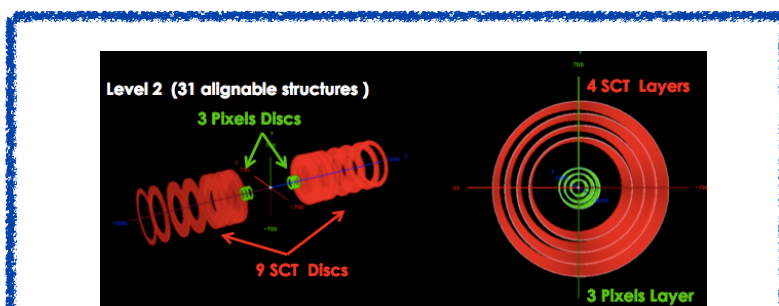
## GLOBAL CHI2 ALIGNMENT ALGORITHM

## Silicon alignment levels

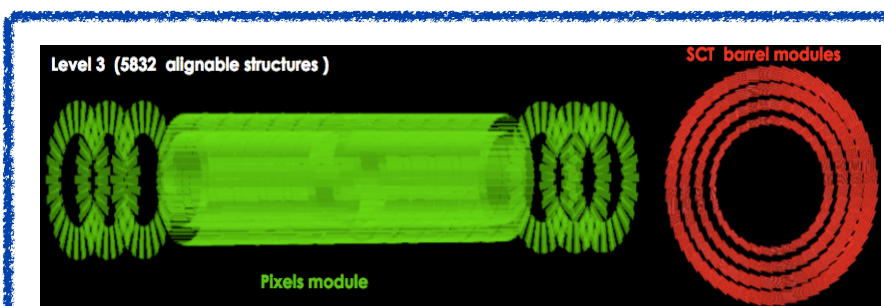
The ID alignment is done on several levels corresponding to different granularity of the detector.



**LEVEL 1, 4 structures (24 DoFs):**  
Whole pixel detector  
SCT barrel  
SCT end-cap A and B



**LEVEL 2, 31 structures (186 DoFs):**  
Layers in PIXEL's and SCT barrel  
Discs in PIXEL's and SCT end-cap

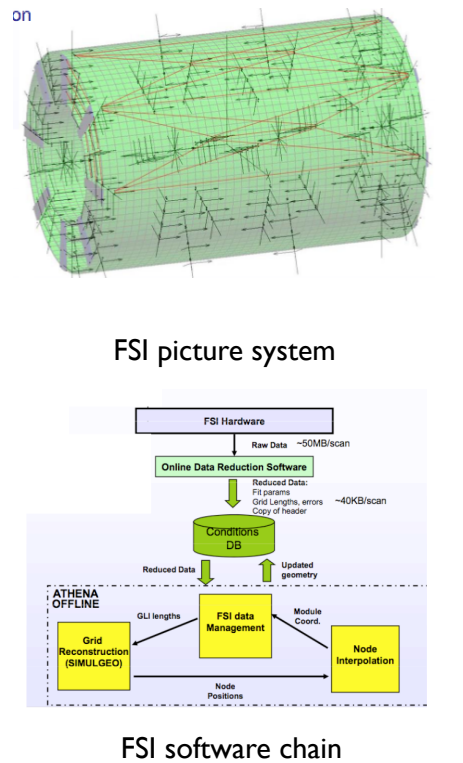


**LEVEL 3: 5832 structures (36k DoFs):**  
Module level in PIXEL's and SCT detector

There are also intermediate levels that combine different substructures as ladders, rings or halfshells.

## FSI ( FREQUENCY SCANNING INTERFEROMETRY)

A laser alignment system (geodetic grid of length measurement between nodes) is installed in the SCT detector. The FSI provides knowledge about the stability of the detector with time (842 grid line length are measured simultaneously each 10 min). Using FSI, one can achieve a precision <1μm along ID length (precision in 3D ~5μm). It can measure relative rotations (clocking of barrel) and radial deformation. Will be used intensively in the early runs.

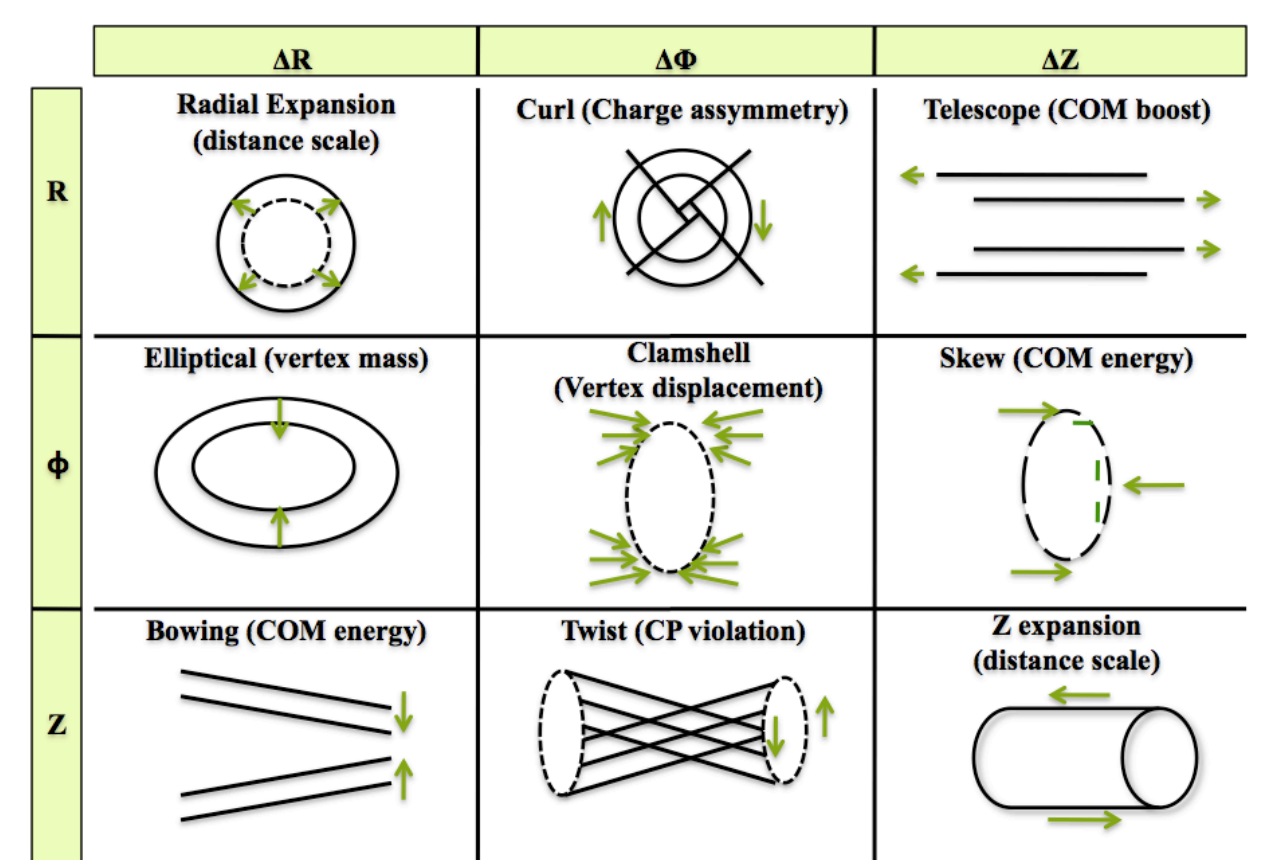


## Weak modes

The Weak Modes are deformations that leave the track  $\chi^2$  almost unchanged.

There are some tools to determine these weak modes:

- Cosmic rays and beam halo.
- Vertex and beam spot constraint.
- External surveys.
- Use FSI Information.



## Alignment with real data (M8+ Cosmics)

An alignment was performed using the cosmic rays data obtained in 2008.

The residuals distributions using each silicon algorithm are showed in the plots:

